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4 Band-limited topographic mass distribution generates full-spectrum

5 gravity field – gravity forward modelling in the spectral and spatial

6 domains revisited

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20 Key points

- Band-limited topographic mass model generates a full-spectrum gravity field
- p-th power of topography expanded to n contributes to degree $p \times n$ to potential
- Spatial and spectral gravity forward-modelling techniques agree at 10^{-5} level

24 Abstract

Most studies on gravity forward modelling in the spectral domain truncate the gravitational 25 potential spectra at a resolution commensurate with the input topographic mass model. This 26 implicitly assumes spectral consistency between topography and implied topographic potential. 27 28 Here we demonstrate that a band-limited topographic mass distribution generates gravity signals with spectral energy at spatial scales far beyond the input topography's resolution. The spectral 29 energy at scales shorter than the resolution of the input topography is associated with the 30 contributions made by higher-order integer powers of the topography to the topographic 31 32 potential. The p-th integer power of a topography expanded to spherical harmonic degree n is 33 found to make contributions to the topographic potential up to harmonic degree p times n. New 34 numerical comparisons between Newton's integral evaluated in the spatial and spectral domain 35 show that this previously little addressed truncation effect reaches amplitudes of several mGal for topography-implied gravity signals. Modelling the short-scale gravity signal in the spectral 36 domain improves the agreement between spatial and spectral domain techniques to the microGal-37 level, or below 10⁻⁵ in terms of relative errors. Our findings have important implications for the 38 use of gravity forward modelling in geophysics and geodesy: The topographic potential in 39 spherical harmonics must be calculated to a much higher harmonic degree than resolved by the 40 input topography if consistency between topography and implied potential is sought. With the 41 improved understanding of the spectral modelling technique in this paper, theories and computer 42 implementations for both techniques can now be significantly better mutually validated. 43

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Key words: Gravity, topography, gravity forward modelling, spatial modelling, spectral
 modelling

47 **1 Introduction**

Gravity forward modelling denotes the computation of the gravitational signal (e.g., in terms of 48 gravitational potential, gravity disturbances or gravity gradients) induced by a mass-density 49 50 distribution, as given, e.g., through topographic mass models. Techniques for gravity forward modelling are routinely applied in potential field geophysics, e.g., to aid the interpretation of 51 observed gravity [Jakoby and Smilde, 2009] and in physical geodesy, e.g., in the context of geoid 52 modelling [Tziavos and Sideris, 2013]. Common to all gravity forward modelling techniques is 53 the evaluation of the well-known Newton's integral, which can be done both in the spatial 54 domain and spectral domain [Kuhn and Seitz, 2005; Wild-Pfeiffer and Heck, 2007]. 55

- Spatial domain forward modelling [e.g., *Forsberg*, 1984; *Nagy et al.* 2000; *Kuhn et al.* 2009; *Tsoulis et al.* 2009; *Hirt et al.*, 2010; *Grombein et al.*, 2013; *d'Urso*, 2014] directly evaluates Newton's integral. This is commonly done by decomposing the topographic mass model into elementary bodies (e.g., prisms, tesseroids, polyhedra) along with numerical/analytical integration to obtain the gravitational potential implied by the masses. This technique is also known as Newtonian integration.
- Spectral domain forward modelling [e.g., Sünkel, 1985; Rummel et al. 1988; Tenzer, 63 • 2005; Wieczorek, 2007; Novák, 2010; Hirt and Kuhn, 2012] evaluates Newton's integral 64 through transformation into the spectral domain. This commonly utilizes spherical-65 harmonic series expansions for conversion of spherical harmonic topography models to 66 67 the implied gravitational potential. Formulated as a three-step procedure, in spectral forward modelling (i) the topographic surface (i.e., the topographic heights sampled on a 68 geographical grid) and its integer powers are expanded into spherical harmonic series. 69 70 The resulting coefficients are (ii) directly used to yield the topographic potential in 71 spherical harmonics (as a series expansion of the integer powers of the topography), and (iii) gravity effects are obtained from the topographic potential coefficients in the spatial 72 domain through spherical harmonic synthesis. 73

74 Many previous studies concerned with spectral domain forward modelling use a spherical 75 harmonic topography model to some fixed spectral resolution (as specified through the maximum harmonic degree of the series expansion, e.g., 360) for the calculation of implied 76 gravitational potential with identical resolution. As such, spectral consistency (i.e., identical 77 78 spectral band widths) of the topography and generated gravitational potential is implicitly assumed. Examples of such works are Sünkel [1985]; Rummel et al. [1988]; Rapp [1989]; Rapp 79 and Pavlis [1990]; Pavlis and Rapp [1990]; Tsoulis [2001]; Kuhn and Featherstone [2003]; 80 Wild-Pfeiffer and Heck [2007]; Wieczorek [2007]; Mahkloof [2007]; Novák [2010]; Balmino et 81 al. [2012]; Hirt et al. [2012]; Hirt and Kuhn [2012]; Tenzer et al. [2012]; Bagherbandi and 82 Sjöberg, [2012]; Novák and Tenzer [2013]; Gruber et al., [2014], among others. However, as 83 will be shown in this paper, this mostly unwritten assumption does not hold, see also Heck and 84 85 Seitz [1991], and Papp and Wang [1996].

86 As the main topic of the present study we demonstrate that a band-limited spherical harmonic 87 topography generates (in good approximation) a full-banded gravitational potential. We show 88 that the generated gravitational signal features additional high-frequency spectral energy beyond and far beyond the initial band limitation of the input (source) topography. This effect, which 89 causes "spectral inconsistency" between topography and gravitational signal, is fairly 90 91 straightforward to model (Section 2), but mostly neglected in the literature. We will show this 92 effect to be responsible for spurious discrepancies in numerical comparisons among gravitational 93 signals from spectral and space domain techniques (Section 3).

In previous studies concerned with comparisons among gravitational effects from the two
techniques, notable discrepancies were encountered or reported. In terms of *relative errors*(defined here as the ratio between the maximum discrepancy between spatial and spectral
forward modelling and the maximum gravitational signal over some test area)

- *Kuhn and Seitz* [2005] found relative errors at the level of ~3 % for the gravitational
 potential, for expansions to harmonic degree 1440,
- Wild-Pfeiffer and Heck [2007] yielded relative errors of ~4.5 % for gravity gradients over a global test area (maximum signals of ~6.7 Eötvos (1 Eötvös = 10⁻⁹ s⁻²) versus a maximum discrepancy of ~0.3 Eötvos),
- Wang et al. [2010] encountered relative errors at the level of ~10% or up to ~60 mGal(1 mGal = 10⁻⁵ ms⁻²) discrepancies for gravity disturbances over various mountainous test areas (e.g., Himalayas, Rocky Mountains, Andes) for expansions to harmonic degree 2700,
- Balmino et al. [2012] published discrepancies at the level of ~10 % (or up to ~48 mGal)
 for gravity disturbances over their test area 'Marocco', and
- Novák and Tenzer [2013] found relative errors of ~0.8% for gravity gradients at satellite altitude over a regional test profile crossing the Andes (maximum discrepancy of 0.5 × 10⁻² Eötvös versus signal of 5.8 Eötvös),

please also see discussion in Section 4. The five aforementioned studies have in common that they do not investigate the spectral inconsistency between topography and implied gravity as a key candidate for the differences encountered. While the spatial domain technique (Newtonian integration) implicitly takes into account the additional high-frequency spectral constituents beyond the band width of the input topography, explicit consideration is required in the spectral domain for improved mutual consistency of gravity effects from the two forward modelling techniques.

From our literature review, the spectral inconsistency among topography and gravity is only little 119 discussed in the context of gravity forward modelling, though the mechanisms affecting the 120 spectral characteristics are by no means unknown. Papp and Wang [1996] modelled the 121 122 gravitational potential in spherical harmonics and noticed truncation effects in comparisons with Newtonian integration. They made the important statement that "[...] the spectral characteristics 123 124 of the spherical harmonics in forward local gravity modelling are different from that of the results obtained from rectangular prism integration." [Papp and Wang, 1996, p63]. Heck and 125 126 Seitz [1991] investigated nonlinear effects in the geodetic boundary value problem, showing that the multiplication of two series expansions to represent second-order effects increases the 127 maximum harmonic degree by a factor of 2. In the context of the frequently used geodetic 128 reference system GRS80 (Moritz, [2000]), another analogy is found [Claessens, 2013, pers. 129 comm.]. A rotating mass-ellipsoid (as "example" for a most simple spherical harmonic 130 131 topography) generates a gravitational field with notable spectral energy at even multiples of 132 degree 2.

The first and main aim of the present study is the introduction of a novel contribution scheme for 133 spectral domain forward modelling that relies on spherical harmonic topographic mass models of 134 some given resolution as input data. Our scheme provides the spectral constituents of the implied 135 gravity signal at all spatial scales – to and beyond the input topography's resolution. As second 136 aim of the study, we use the contribution scheme in new comparisons between spectral and 137 spatial forward modelling techniques to demonstrate that high-frequency gravity signals (beyond 138 the input topography's resolution) are naturally 'delivered' by space domain techniques, while 139 the spectral technique requires explicit modelling. Our new contribution scheme is suitable to do 140 this. As further aims, we demonstrate the practical relevance of the higher-order integer power 141 contributions of the topography to the implied potential, the importance of the computation point 142 height in both techniques, and the convergence of series expansions used for field continuation in 143 the spectral domain. 144

The paper is organized as follows. Section 2 sets the mathematical framework for spatial and spectral domain forward modelling, exemplified here for gravity disturbances as radial derivatives of the gravitational potential. Section 3 then presents a numerical case study which (i) analyses the spectra of the topography-implied gravitational potential and (ii) compares gravity from spatial and spectral domain forward modelling. The case study demonstrates that explicit modelling of the high-frequency spectrum in the spectral domain significantly improves the agreement with spatial forward modelling. Section 4 discusses the results, also in the context
of the literature, and Section 5 draws conclusions for some present and future gravity forward
modelling applications.

154 **2 Theory**

We start by introducing H_{nm} as a short-hand for the fully-normalized spherical harmonic coefficients (SHC) $(\overline{HC}, \overline{HS})_{nm}$ of a topography model, whereby *n* denotes the harmonic degree, and *m* the harmonic order. The coefficients H_{nm} are expanded into the spherical harmonic series

158
$$H(\varphi,\lambda) = \sum_{n=0}^{n_{\max}} \sum_{m=0}^{n} (\overline{HC}_{nm} \cos m\lambda + \overline{HS}_{nm} \sin m\lambda) \overline{P}_{nm}(\sin \varphi)$$
(1)

to maximum degree n_{max} in order to describe the topographic height $H(\varphi, \lambda)$ at geocentric latitude φ and longitude λ . The term $\overline{P}_{nm}(\sin \varphi)$ denotes the fully-normalized associated Legendre function of degree n and order m. Topographic heights H are laterally variable and provide the height of the topographic surface with respect to some height reference surface, e.g., mean sea level. The harmonic coefficients H_{nm} are assumed to be readily available from a spherical harmonic analysis of some global topography model (cf. Section 3).

165 The spherical harmonic topography model expanded to maximum degree n_{max} is used as input 166 (i.e., source model that generates the topographic gravity field) both for the spatial domain 167 (Section 2.1) and spectral domain forward modelling (Section 2.2) along with some constant 168 mass-density value ρ (e.g., of standard rock). This is done in order to use identical topographic 169 mass models as "source of the gravity field" in both techniques. We acknowledge that laterally-170 varying mass-density values could be used as a refinement [e.g., *Kuhn and Featherstone* 2003; 171 *Eshagh*, 2009], but this is not necessary for the topic of our study.

172

For reasons of simplification, we consistently use the spherical approximation for forward 173 174 modelling with both techniques. In the spherical approximation, the topographic height H is "mapped" onto the surface of a reference sphere with some constant radius R (see, e.g., Balmino 175 et al., [2012]). The spherical approximation is chosen here over the more advanced ellipsoidal 176 approximation [Claessens and Hirt, 2013; Wang and Yang, 2013] which uses a reference 177 ellipsoid instead of a reference sphere. The spherical approximation level chosen is completely 178 179 suitable to compare the spectral characteristics of the topography with the implied topographic potential. The spherical approximation is also used for reasons of consistency with the vast 180 majority of previous works on forward-modelling (see references in the introduction). 181

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Figure 1. Geometry of a tesseroid (left) replaced by a rectangular prim with first-order mass equivalence and identical vertical extension (right). Note, while the intersection points Q and Q' of the centre line with the tesseroid's top and bottom surfaces are identical with that of the prism, the corner points are not (e.g. $Q_1 \neq \tilde{Q}_1$ and $Q_2 \neq \tilde{Q}_2$).

Spatial domain forward modelling of the global topographic masses is based on *discretised* Newtonian integration following the concepts applied in, e.g., *Kuhn* [2000], [2003] and *Kuhn et al.* [2009]. In this approach the mass distribution considered is discretised by a set of regularly shaped mass elements (e.g. point mass, prism or tesseroid) and the gravitational signal is obtained through superposition of the individual effects from each mass element. This principle is exemplified by Eq. (2) through Newton's integral for the gravitational potential δV generated by the mass distribution *M* replaced by the sum over the gravitational potentials δV_n generated

197 by N_{elem} mass elements m_n $(n = 1, ..., N_{elem})$.

198
$$\delta V = G \iiint_{M} \frac{dm}{l} \approx \sum_{n=1}^{N_{elem}} G \iiint_{m_n} \frac{dm_n}{l_n} = \sum_{n=1}^{N_{elem}} \delta V_n$$
(2)

In Eq. (2), *G* is the universal gravitational constant, and dm and dm_n denote infinitesimally small mass elements describing *M* and m_n , respectively. The Euclidian distances *l* and l_n are defined between the computation point *P* and the running integration points within *M* and m_n , respectively. We calculate the gravitational attraction δg_z (radial derivative of the potential, also known as gravity disturbance) along the vertical at *P* (i.e., in opposite direction to the surface normal on a reference sphere) via

205
$$\delta \vec{g} = (\delta g_x, \delta g_y, \delta g_z)^T = \operatorname{grad}(\delta V) \approx \sum_{n=1}^N \operatorname{grad}(\delta V_n)$$
 (3)

Where grad denotes the gradient and δg_x , δg_y , δg_z are the vector components of $\delta \vec{g}$ given with respect to a topocentric coordinate system *x*, *y*, *z* at *P* (cf. Fig. 1). The coordinate axes of the topocentric coordinate system are orientated so that the *x*-axis points towards geodetic north, the *y*-axis towards geodetic east and the *z*-axis towards the zenith (or radial direction).

The approximation errors introduced by Eqs. (2) and (3) depend on how well the elements m_n 210 approximate the original mass distribution M. The use of rectangular prisms is approximate 211 because the vertical faces of adjoining prisms are not parallel (they intersect or exhibit wedge-212 like gaps). An upper limit of the magnitude of this effect on the order of 2 μ Gal (= 2×10⁻⁸ ms⁻²) 213 in this study is obtained from the numerical comparisons between the space and spectral domain 214 215 techniques (Section 3.4). In future application of the space domain technique, polyhedra [e.g., Benedek, 2004; d'Urso, 2014] can be a viable alternative to prisms because they avoid the prism 216 approximation. In order to reduce approximation errors caused by mass elements located in the 217 vicinity of the computation point we divide the gravitational attraction according to 218

219
$$\delta \vec{g} = \delta \vec{g}^{SH} + \delta \vec{g}^{RM}$$
 (4)

where $\delta \vec{g}^{SH}$ is the gravitational attraction of a shell (or more generally a layer) of constant thickness and $\delta \vec{g}^{RM}$ is the gravitational attraction of all masses residual to the shell. The shell is selected such that no residual masses are present at the location of the computation point. In this study we model the topographic masses (including bathymetry and ice sheets, cf. Sect. 3.2) in spherical approximation, thus $\delta \vec{g}^{SH}$ corresponds to the gravitational attraction of a spherical shell (often termed Bouguer shell) and $\delta \vec{g}^{RM}$ corresponds to the spherical terrain correction [e.g., *Kuhn et al.* 2009].

For the practical evaluation of $\delta \vec{g}$, in this study, we replace the topographic masses by a series of tesseroids in spherical approximation, which are further approximated by rectangular prisms with first-order mass equivalence and identical vertical extension. The methodology and corresponding formulae are provided by e.g. *Anderson* [1976]; *Grüninger* [1990]; *Kuhn* [2000] and *Heck and Seitz* [2007] and will be briefly outlined here.

Tesseroids in spherical approximation are spherical mass elements bounded by surfaces of constant geocentric latitude (φ_1, φ_2), longitude (λ_1, λ_2), and geocentric radii ($r_1 = R + H_1, r_2 = R + H_2$) and can be considered as the *natural* mass element when using heights *H* (here from Eq. 1) given on a regular geocentric latitude-longitude grid (Fig. 1). The 236 geometrical centre $Q_0(\varphi_0, \lambda_0, r_0)$ and dimensions $(\Delta \varphi, \Delta \lambda, \Delta r)$ of the tesseroid are given by (cf. 237 Fig. 1)

(5)

238 $\varphi_0 = (\varphi_1 + \varphi_2)/2; \quad \Delta \varphi = \varphi_2 - \varphi_1$

239
$$\lambda_0 = (\lambda_1 + \lambda_2)/2; \quad \Delta \lambda = \lambda_2 - \lambda_1$$

240 $r_0 = (r_1 + r_2)/2;$ $\Delta r = r_2 - r_1$

As the integral over m_n in Eq. (2) cannot be exactly solved for a tesseroid [cf. *Heck and Seitz* 2007] we approximate the tesseroid by a rectangular prism centred at the same location Q_0 with its edges being parallel to the axes x', y', z' of a topocentric coordinate system located at the centre of the tesseroid's top surface $Q(\lambda_0, \varphi_0, r_2)$ which coincides with the centre of the prism's top surface (cf. Fig. 1). For first-order mass equivalence and identical heights the dimension of the prism is given by [e.g., *Anderson*, 1976; *Grüninger*, 1990; *Heck and Seitz*, 2007]:

247
$$\Delta x = r_0 \Delta \varphi; \quad \Delta y = r_0 \cos \varphi_0 \Delta \lambda; \quad \Delta z = \Delta r$$
 (6)

We compute the gravitational attraction of the rectangular prisms based on the well-known analytical formulae as provided by e.g. *Mader* [1951]; *Nagy* [1966]; *Nagy et al.* [2000, 2002] and modified to a numerically more stable expression shown in e.g. *Kuhn* [2000] and *Heck and Seitz* [2007]. Within our numerical studies we only focus on the *z*-component δg_z (the gravity disturbance) of the vector $\delta \overline{g}$ (cf. Eq. 3) at the location of the computation point *P* (cf. Fig. 1).

253 2.2 Spectral domain forward modelling

The technique description is largely based on the work by *Hirt and Kuhn* [2012], but modified here to accommodate for the additional high-frequency spectral constituents beyond the bandwidth of the input topography.

257 2.2.1 Topographic potential in the spectral domain

The key ingredient for spectral domain forward modelling are topographic height functions and their integer powers. We define the dimensionless topographic height function (THF) as ratio of the topographic height *H* and the reference radius *R*. The THF raised to arbitrary integer power $p \ (p \in \Box)$ then reads

262
$$H^{(p)} = \frac{H^p}{R^p}$$
 (7)

in the spatial domain. The spectral domain representation of $H^{(p)}$, denoted here with $H_{nm}^{(p)} = (\overline{HC}, \overline{HS})_{nm}^{(p)}$, is obtained through spherical harmonic analyses of the $H^{(p)}$. The $H_{nm}^{(p)}$ of the THF are thus related to their spatial domain counterpart $H^{(p)}(\varphi, \lambda)$ via

266
$$H^{(p)}(\varphi,\lambda) = \sum_{n=0}^{N_{\text{max}}} \sum_{m=0}^{n} (\overline{HC}_{nm}^{(p)} \cos m\lambda + \overline{HS}_{nm}^{(p)} \sin m\lambda) \overline{P}_{nm}(\sin \varphi)$$
(8)

where the maximum harmonic degree N_{max} is commonly set identical with the maximum degree n_{max} of the topography model, and thus considered independent of the integer power p, e.g.,

$$269 \qquad N_{\rm max} = n_{\rm max} \,. \tag{9}$$

The vast majority of past works on spectral domain forward modeling relies [implicitly] on Eq. (9), see the list of cited references in the introduction. As novelty of this study, we here extend the spectral forward modeling technique by introducing N_{max} as a function of the integer power *p* for the THFs, *e.g.*,

$$274 \qquad N_{\rm max} = pn_{\rm max} \tag{10}$$

and therefore

276
$$H^{(p)}(\varphi,\lambda) = \sum_{n=0}^{pn_{\max}} \sum_{m=0}^{n} (\overline{HC}_{nm}^{(p)} \cos m\lambda + \overline{HS}_{nm}^{(p)} \sin m\lambda) \overline{P}_{nm}(\sin \varphi) \quad .$$
(11)

Increasing the maximum harmonic degree N_{max} from n_{max} to pn_{max} requires oversampling of the $H^{(p)}$ by factor p prior to computing the $H_{nm}^{(p)}$ via the spherical harmonic analyses. Compared to the maximum harmonic degree n_{max} of the topography model, twice the spectral resolution $(2 n_{\text{max}})$ is thus taken into account for the squared THF $H_{nm}^{(2)}$, and three times the resolution $(3 n_{\text{max}})$ for the cubed THF $H_{nm}^{(3)}$, and so forth.

The topographic gravitational potential (short: topographic potential) coefficients V_{nm} are calculated via a standard series expansion into powers p of the THFs $H_{nm}^{(p)}$ [after Wieczorek 2007, Hirt and Kuhn 2012]:

285
$$V_{nm} = \frac{1}{2n+1} \frac{4\pi R^3 \rho}{M} \sum_{p=1}^{p \max} \frac{\prod_{i=1}^{p} (n+4-i)}{p!(n+3)} H_{nm}^{(p)}$$
(12)

where V_{nm} is the short-hand for the $(\overline{VC}, \overline{VS})_{nm}$ SHCs of the topographic potential, p_{max} is the maximum integer power of the series expansion, and *M* is the mass of the planet. From *Hirt and Kuhn* [2012, Fig. 1 ibid], the higher the resolution of the input topography n_{max} , the more integer powers *p* must be taken into account in Eq. (12) for convergence. The number of terms also



Figure 2. Contribution scheme for spectral domain gravity forward modelling: Contributions of integer powers *p* of
 the topography to the topographic potential as a function of the integer power (vertical axis) and the *p*-th multiple of
 the input bandwidth (horizontal axis)

increase with the range of the heights relative to the reference radius *R*, see *Claessens and Hirt* [2013]. For degree-2160 Earth topography mass models, it was shown that $p_{max} = 8$ yields truncation errors (resulting from dropping terms with p > 8) well below the mGal level, cf. *Hirt and Kuhn* [2012]. Another convergence analysis has shown truncation errors below the mGal level for degree 360 models and $p_{max} = 4$ [*Wieczorek* 2007].

Eq. (12) can easily be evaluated for individual integer powers p, instead of calculating the sum from p = 1 to p_{max} . Then, the contribution of the p-th integer power of the topography to the topographic potential is obtained. Eq. (12) can also be evaluated separately for harmonic band $n \in [0 \ n_{\text{max}}]$ and for p-th multiples thereof: $n \in [(p-1)n_{\text{max}} + 1 \ pn_{\text{max}}]$. This leads to a new, generalized contribution scheme for spectral domain forward modelling shown in Fig. 2.

The left column (light grey boxes in Fig. 2) shows the contribution of the *p* -th integer power of the topography limited to n_{max} , these were investigated or calculated e.g., by *Rummel et al.* [1988]; *Tsoulis* [2001]; *Wild-Pfeiffer and Heck* [2007]; *Wieczorek* [2007]; *Mahkloof* [2007]; *Novák* [2010]; *Balmino et al.* [2010]; *Hirt and Kuhn* [2012], among many others.

New are the columns with $n > n_{max}$ (dark grey boxes in Fig. 2). They reflect the additional high-

frequency signals associated with forming powers of the THF. Raising the THF to power p=2doubles the band-width of the input topography, and power p=3 triples the input band width,

leading to the triangular contribution scheme in Fig. 2. This can be generalized to the statement:

313 The *p*-th integer power of a topography expanded to spherical harmonic degree n_{max} 314 contributes to the topographic potential up to degree *p* times n_{max} .

This finding can be easily verified by the frequencies present in the p-th powers of sine or 315 cosine-functions (cf. Fig. 3). For instance, raising the sine function with frequency f_0 to the 2nd 316 power doubles the frequency, e.g. $2f_0$, compared to the sine function. For the 3^{rd} power the 317 maximum frequency present is $3f_0$ and so forth for higher powers (Fig. 3). Raising the sine 318 function to infinite power will result in an infinite sequence of equidistant delta functions of 319 which the Fourier transform is also an infinite series of equidistant delta functions covering 320 infinite multiples of f₀ [e.g., *Bringham*, 1988, p21]. This behaviour is exemplified with a sine 321 function raised to power p=1000 in Fig. 3. 322



323

Figure 3. Top: Sine-functions raised to integer powers p = 1,2, 3 and 1000, Bottom: Fourier-spectra (magnitudes) of
 the powered sine functions. The bottom panel exemplifies the gain in band-width as the power p increases. Variable
 x in radian, frequencies normalized to interval [0 1].

327

Applying this analogy to the topography function H expressed through a series of sine and cosine

functions (cf. Eq. 1) covering the spectral band to a maximum degree n_{max} , e.g. $n \in [0 \ n_{\text{max}}]$ the

- spectral band of the squared function extends to $2n_{\text{max}}$, as noted by *Heck and Seitz* [1991].
- 331 Ultimately, raising H to infinite power will result in a function covering the full spectrum even
- though the original function was band-limited. This behaviour can also be verified by analysing
- the spectra of the powered THFs (Sect. 3.3), thus confirming the contribution scheme. Further
- evidence in support of the contribution scheme is gathered by comparisons between gravity from
- space and spectral domain techniques (Sect. 3.4).

336 **2.2.2 Synthesis of functionals of the potential**

The V_{nm} can be used to calculate the topographic potential or various functionals thereof in the spatial domain at the three-dimensional coordinates geocentric latitude φ , longitude λ and geocentric radius *r* via spherical harmonic synthesis [e.g., *Holmes and Pavlis* 2008; *Hirt* 2012]. Here we evaluate the frequently used gravity disturbance δg (being the radial derivative of the gravitational potential, equivalent to δg_z introduced in Sect. 2.1), defined through [after *Torge* 2001, p 271]:

$$\delta g(\varphi, \lambda, r) = -\frac{\partial V}{\partial r} = \frac{GM}{r^2} \sum_{n=2}^{n\max} (n+1) \left(\frac{R}{r}\right)^n \sum_{m=0}^n (\overline{VC}_{nm} \cos m\lambda + \overline{VS}_{nm} \sin m\lambda) \overline{P}_{nm}(\sin \varphi)$$
(13)

As geocentric radius r of the evaluation points, we choose the surface of the topographic mass model, as represented through

346
$$r = r(\varphi, \lambda) = R + H(\varphi, \lambda)$$
 (14)

This is done in order to account for the effect of gravity attenuation with height [cf. *Hirt* 2012]. For reasons outlined in *Hirt* [2012], and *Hirt and Kuhn* [2012], evaluation of Eq. (13) in terms of dense grids can be computationally demanding when the radii of evaluation $r(\varphi, \lambda)$ vary along parallels (φ = constant), as in Eq. (14). A numerically efficient and precise approximate solution is obtained here via field continuation of gravity disturbances with higher-order gradients of δg [*Hirt and Kuhn*, 2012]

353
$$\delta g^{k \max}(\varphi, \lambda, r) \approx \sum_{k=0}^{k \max} \frac{1}{k!} \frac{\partial^k \delta g}{\partial r^k} \bigg|_{r=R+H_{ref}} (H-H_{ref})^k$$
(15)

where k_{max} is the maximum order of the series expansion, H_{ref} is some mean reference height for acceleration of convergence and $\partial^k \delta g / \partial r^k$ is the *k*-th order radial derivative of δg calculated at a constant height $r = R + H_{ref}$ via [*Hirt*, 2012]

357
$$\frac{\partial^{k} \delta g}{\partial r^{k}} = (-1)^{k} \frac{GM}{r^{k+2}} \sum_{n=2}^{n} (n+1) \left\{ \prod_{i=1}^{k} (n+i+1) \right\} \left(\frac{R}{r} \right)^{n} \times \sum_{m=0}^{n} (\overline{VC}_{nm}^{p\max} \cos m\lambda + \overline{VS}_{nm}^{p\max} \sin m\lambda) \overline{P}_{nm}(\sin \varphi) \right\}.$$
(16)

358 **3 Numerical study**

359 **3.1 General**

A numerical study is carried out based on the publicly available RET2012 topography model 360 (Sect 3.2) with the goals to analyse the spectra of the THFs (Sect. 3.3.1) and of their 361 contributions to the topographic potential (Sect. 3.3.2) in order to investigate the signal strengths 362 363 of these contributions for gravity disturbances in the spatial domain. The study then systematically compares gravity disturbances from spatial and spectral domain forward 364 modelling as a function of the *p*-th integer power contributions and maximum harmonic degree 365 $N_{\text{max}} = pn_{\text{max}}$ taken into consideration (Sect. 3.4). A main motivation for the numerical study is 366 367 the verification of the contribution scheme for spectral domain forward modelling (Fig. 2).

368 For the spherical harmonic synthesis of the topography H [Eq. (1)], and analyses of the THFs $H_{nm}^{(p)}$ [Eq. (7)] we use the SHTools package (www.shtools.org), and for spherical harmonic 369 synthesis of gravity disturbances and their k-th order radial derivatives [cf. Eq. (16)] a 370 modification of the harmonic synth software [Holmes and Pavlis, 2008]. Both packages deploy 371 the routines by Holmes and Featherstone [2002] for the stable computation of the associated 372 Legendre functions $\overline{P}_{nm}(\sin \phi)$ to degree n=2700. Given that the $\overline{P}_{nm}(\sin \phi)$ are subject to 373 numerical instabilities which increase for n > 2700 [Holmes and Featherstone, 2002], we 374 confine all of our numerical tests to 375

376
$$N_{\text{max}} = pn_{\text{max}} \le 2700$$
. (17)

As a consequence, the band width $\begin{bmatrix} 0 & n_{max} \end{bmatrix}$ of the input topography must be chosen sufficiently narrow to allow for accurate evaluation of the high-frequency *p*-multiples of $\begin{bmatrix} 0 & n_{max} \end{bmatrix}$. Among many possible band widths, we have chosen the input band $\begin{bmatrix} 0 & n_{max} = 360 \end{bmatrix}$ as our example for band-limited topographic mass models. For this band, calculation and analyses of multiples of the input band $\begin{bmatrix} 0 & n_{max} = 360 \end{bmatrix}$ up to p = 7 is safely possible. As will be shown, this is sufficient to verify the contribution scheme in Fig. 1.

We acknowledge that algorithms for the stable computation of $\overline{P}_{nm}(\sin \varphi)$ to arbitrary degree have been developed [*Fukushima*,2012a; 2012b], which could be used in a future case study to ultra-high degree, once tested implementations for spherical harmonic analyses become available (for spherical harmonic synthesis software to ultra-high degree see e.g., *Bucha and Janák*[2013]).

388 3.2 Data and constants

As model representing the topographic masses, we use the freely-available spherical harmonic 389 data set RET2012 (rock-equivalent topography model) of Curtin University's Earth2012 model 390 suite (URL: http://geodesy.curtin.edu.au/research/models/Earth2012/, 391 file Earth2012.RET2012.SHCto2160.dat). This allows replication of our study. Based on a range of 392 393 input data sets, RET2012 represents the masses of the visible topography, of the oceans and major inland lakes, and major ice-sheets using a single constant mass-density of $\rho = 2670$ kg m⁻ 394 ³. Rock-equivalent heights of ice and water-masses were derived through mathematical 395 compression into rock equivalent mass layers [e.g., Rummel et al., 1988], see Hirt et al. [2012] 396 and Hirt [2013] for details on the procedures applied to generate the RET2012 SHCs H_{nm} . 397 Though the SHCs of RET2012 are available to degree and order 2160, we use this model only 398 from degree and order 0 to degree and order 360 (= n_{max}). As such, only the RET2012 spectral 399 band of harmonic degrees 0 to 360 defines the input (source) topography in this study. 400

For our tests of the two forward-modelling techniques, we use exactly the same topographic 401 mass model as input: In the spatial domain technique: heights $H(\varphi, \lambda)$ synthesized from the 402 RET2012SHCs H_{nm} at various resolutions, and in the spectral domain technique the H_{nm} 403 directly as input topography. Also used with identical numerical values in both techniques are 404 the topographic mass density $\rho = 2670$ kg m⁻³, reference radius R = 6,378,137 m (semi-major 405 axis of GRS80), [Moritz, 2000], the universal gravitational constant $G = 6.67384 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1}$ 406 s⁻² [Mohr et al. 2012, p 72] and total Earth's mass (including atmosphere) $M = 5.9725810 \times 10^{24}$ 407 408 kg (from the GM product of GRS80, Moritz [2000]).

409 **3.3 Spectral analyses**

410 **3.3.1 Topography**

To derive the spectra of the THFs, we (i) synthesized RET2012 heights H in spectral band 411 $[0 \quad n_{max} = 360]$ in terms of regularly-spaced geocentric latitude-longitude grid of 2 arc-min 412 resolution (5400 \times 10800 heights), (ii) normalized this grid with R, (iii) raised the resulting THFs 413 to integer power $p \ge 1$, and (iv) analysed harmonically the powered THFs $H^{(p)}$ with SHTools 414 (algorithm by *Driscoll and Healy* [1994]). This procedure gave us the $H_{nm}^{(p)}$ -SHCs to a maximum 415 degree and order n = m = 2700. Note that the THFs assume very small values as the power 416 increases (e.g., p=5, THF $\approx 10^{-20}$ for heights around 1 km). To avoid possible numerical 417 problems in the analysis associated with small numbers, we scaled each THF with its maximum 418

value before the analysis and undid this scaling at coefficient level. The dimensionless degreevariances of the THFs

421
$$\sigma H_n^{(p)2} = \sum_{m=1}^n \left(\overline{HC}_{nm}^{(p)2} + \overline{HS}_{nm}^{(p)2} \right)$$
(18)

422 are shown in Fig. 4 as a function of the degree n for the first four integer powers.



424 **Figure 4.** Degree variances of the first four integer powers p of the topographic height function (*H/R*) band-limited 425 to degree 360

423

For the linear THF $H^{(1)}$, the spectrum slowly decays from degree 0 to degree 360, drops by 25 426 orders of magnitude at degree 361, and stays at the level of $\sim 10^{-37}$ for all other degrees (noise 427 level as given by the computational precision). This behaviour is expected, given the band-width 428 limitation of the input topography to $n_{\text{max}} = 360$. The squared THF $H^{(2)}$ is smaller in amplitude, 429 so features less power than $H^{(1)}$. The spectrum of $H^{(2)}$ slowly decays to degree 360, drops 430 slightly around degree 361, and experiences another slow decay up to degree 720, before falling 431 to noise level. This behaviour shows that the band width of $H^{(2)}$ is extended by factor 2 432 compared to the input band (through rising to power 2). Fig. 4 further shows for the cubed THF 433

434 $H^{(3)}$ significant spectral power in band 0 to 1080 (three times the input band width), and for 435 $H^{(4)}$ significant spectral power to degree 1440 (four times the input band width), Exemplified 436 with the first four integer powers of the THFs, Fig. 4 nicely shows the increase in band width by 437 a factor of *p* with respect to the input band limitation to $n_{max} = 360$.

438 **3.3.2 Potential**

439



440 Figure 5. Potential degree variances of the contributions made by the first six integer powers of the topography to
441 the topographic potential (blue to orange), and of potential degree variances of the [resulting] total topographic
442 potential (black line). Topography is band-limited to degree and order 360.
443

We separately evaluated Eq. (12) for powers p = 1 to 6, giving us the *p*-th contribution of the topography to the topographic potential $V_{nm}^{(p)}$. The dimensionless potential degree variances

446
$$\sigma V_n^{(p)2} = \sum_{m=1}^n \left(\overline{VC}_{nm}^{(p)2} + \overline{VS}_{nm}^{(p)2} \right)$$
(19)

are shown in Fig. 5, as well as the degree variances of the total topographic potential 447 $V_{nm}^{p \max = 6}$ (sum of the six contributions $V_{nm}^{(p)}$). As expected from Fig. 4, the contribution made by 448 p = 1 only possesses power to $n_{max} = 360$, while the other five integer powers contribute to 449 degree 720 (p = 2), to 1080 (p = 3), all the way to degree ~2160 (p = 6). Assuming that degree 450 variances below the level of about ~ 10^{-27} are negligible [see Hirt and Kuhn, 2012], Fig. 5 451 suggests that the powers p = 2 to 5 contribute significantly to $V_{nm}^{p \max = 6}$ in band [361 720], and 452 powers p = 3 to 4 in band [721 1080]. The higher-order contributions of a band-limited 453 topography to the topographic potential tend to contribute largest well beyond the initial input 454 band width, as is seen from the degree variances for p = 6, which are maximum near degree 455 ~700, though originating from a topography band limited to $n_{\text{max}} = 360$. 456

457 **3.4 Spatial analyses**

458 This section compares gravity disturbances from spatial forward modelling (Sect. 2.1) and from spectral forward modelling (Sect. 2.2) over the Himalaya test region ($25^{\circ} < \phi < 35^{\circ}$ and $85^{\circ} < \lambda <$ 459 95°). Because of the most rugged topography and thus gravitational field, this area should serve 460 as a 'worst-case' test area for the technique comparison. Common to the application of both 461 techniques is the dense computation point spacing of 1 arc-min, as well as the arrangement of 462 computation points at the surface of the topography H. This takes into account attenuation of 463 gravity with height. Over areas where H < 0, the computation is carried out at H = 0 (avoiding 464 computations inside the reference sphere). 465

In the spatial domain forward modelling, topographic mass effects induced by the global 466 topography were analytically computed using the discretised Newtonian integration approach 467 described in Sect 2.1. Heights from the topography model were synthesized over the test area in 468 terms of densely spaced grids (20 arc-sec resolution) in spectral band $[0 n_{max} = 360]$. As such, 469 470 the grid of topographic heights is highly oversampled by a factor of 90 (note that the maximum harmonic degree of 360 corresponds to a formal spatial resolution of 1800 arc-sec or ~50 km at 471 the equator). In other words, the spherical harmonic topography is very well represented in the 472 space domain through dense grid point spacing. This oversampling minimizes discretisation 473 errors in spatial domain forward modelling. 474

To reduce computation times, a number of grid resolutions were used as follows: 20-arc-sec within 1° radius, 1 arc-min within 3° radius and 3 arc-min beyond. Because of the quadratic attenuation of gravity with distance, the use of lower grid resolutions outside some radius is common practice (e.g., *Forsberg* [1984]) and – if selected properly – results in approximation errors well below one μ Gal. Figure 6 shows the gravity disturbances from input band $[0 \ n_{max} = 360]$ over our test area, as obtained from the spatial forward modelling (Newtonian integration).



Figure 6. Topographic gravity over the Himalaya test area from space-domain gravity forward-modelling (Newton integration), topographic input band width limited to degree and order 360, unit in mGal (= 10^{-5} m s⁻²). 485

Following the contribution scheme of spectral forward modelling, we computed gravity disturbances as a function of (i) the integer power p, and of (ii) the band width

- 488 $[0 \ n_{\max}], p=1$
- 489 $[(p-1)n_{\max} + 1 pn_{\max}], p > 1,$

respectively. The calculation of each individual contribution made by the topography to the topography-implied gravity disturbance is based on continuation with higher-order gravity gradients to $k_{\text{max}} = 10$ and an average reference height $H_{ref} = 3000$ m [Eqs. (15), (16)]. From a comparison with gravity from direct 3D spherical harmonic synthesis (Eq. 13) at the surface of the topography, approximation errors were below 0.1 µGal (tested for $p_{\text{max}} = 6$ and $N_{\text{max}} = 1440$), so safely negligible.



Figure 7. Single contributions of the topography to the topographic gravity over the Himalaya area $(25^{\circ} < \phi < 35^{\circ}, 85^{\circ} < \lambda < 95^{\circ})$ as a function of the integer power *p* (increasing from top to bottom), and of the *p*-th multiple of the input band (increasing from left to right). Input band is limited to harmonic degree 360, unit in mGal.

The spectral contributions of the topography to the gravity disturbance are displayed in Fig. 7 501 over our test area, whereby the arrangement of panels follows the scheme introduced in Fig. 2. 502 The bulk of the gravity signal originates from the linear term (p=1) evaluated to $n_{max}=360$ (top 503 left). It is seen that from p = 1 to 4 the contributions gradually decrease to the 0.1 mGal level 504 and diminish for higher-order powers. The three columns to the right show the topography-505 506 implied signals in bands [361 720], [721 1080] and [1081 1440]. These are all multiples of the input band width which were not considered in previous 'traditional' spectral domain 507 508 forward modelling. From Fig. 7, the squared and cubed topography generates gravity signals larger than 1 mGal, both within and beyond the input band limitation $n_{\text{max}} = 360$. Contributions 509 510 larger than 10 μ Gal are made by p = 1 to 5 in band [361 720], and p = 3 to 4 in band 511 [721 1080], while the contributions associated with band [1081 1440] are below the 1 µGallevel. Qualitatively, this is in good agreement with the spectral analyses made in Sect. 3.3.2. 512



Figure 8. Residuals between topographic gravity from spatial and spectral forward modelling as a function of (i) maximum integer power p_{max} (increasing from top to bottom) and (ii) maximum harmonic degree N_{max} (increasing from left to right) used in the spectral-domain forward-modelling. Figure should be read together with Figure 7. Differences are in the sense spectral minus spatial modelling, units in mGal.

As the central result of this study, Fig. 8 shows the differences between gravity disturbances 519 from spectral domain and spatial domain forward modelling as a function of the maximum 520 integer power p_{max} used in Eq. (12), and the maximum harmonic degree $N_{\text{max}} = pn_{\text{max}}$ evaluated 521 in the spectral domain. The arrangement of panels follows Fig. 7, but the spectral contributions 522 are accumulated, i.e., sums computed to p_{max} and N_{max} . Selected descriptive statistics (root mean 523 524 square, and maximum absolute value of the difference) are reported in Table 1. From Fig. 7 and Table 1, the agreement among the two techniques improves with increasing p_{max} 525 and increasing N_{max} , from ~5 mGal RMS (31 mGal maximum difference) for $p_{\text{max}} = 1$ and 526 $N_{\text{max}} = n_{\text{max}} = 360$ to an excellent level of 0.3 µGal RMS (~2 µGal maximum difference) for 527 $p_{\text{max}} = 6$ and $N_{\text{max}} \ge 1080$, see Table 1. 528

	Nmax = 360	Nmax = 720	Nmax = 1080	Nmax = 1440
pmax = 1	5.43(31.34)	n/a	n/a	n/a
pmax = 2	1.03(7.83)	0.38 (3.30)	n/a	n/a
pmax = 3	0.96(6.17)	0.03 (0.37)	0.03 (0.36)	n/a
pmax = 4	0.96(6.06)	7.6×10 ⁻³ (7.5×10 ⁻²)	2.5×10 ⁻³ (3.8 ×10 ⁻²)	2.5×10 ⁻³ (3.8×10 ⁻²)
pmax = 5	0.96(6.06)	7.3×10 ⁻³ (6.5×10 ⁻²)	4×10 ⁻⁴ (4.4×10 ⁻³)	4×10 ⁻⁴ (4.1×10 ⁻³)
pmax = 6	0.96(6.06)	7.3×10 ⁻³ (6.4×10 ⁻²)	4×10 ⁻⁴ (2.5×10 ⁻³)	3×10 ⁻⁴ (2.1×10 ⁻³)

529 Table 1. Residuals between spectral and spatial domain forward modelling. Reported are the root-mean square, and530 in brackets the maximum absolute difference between gravity from the two techniques, unit in mGal.

Focussing on the left column ($N_{\text{max}} = n_{\text{max}} = 360$), in Fig. 8, the discrepancies among the two techniques always exceed 5 mGal, irrespective of the p_{max} chosen. The residuals in the left column thus correspond to a 'traditional' comparison between spectral and spatial forward modelling with spectral consistency among topography and gravity presumed. Most importantly, it is the consideration of multiples of the input band width that improves the agreement by a factor of ~100 to the 50 µGal level ($N_{\text{max}} = 2n_{\text{max}} = 720$), and by another factor of ~25 to the µGal level ($N_{\text{max}} = 3n_{\text{max}} = 1080$), also see Table 1.

The comparisons demonstrate that the Newtonian integration inherently 'captures' the additional high-frequency signals (beyond n_{max}), without explicit modelling as must be done in the spectral domain. The remaining discrepancies are likely to reflect numerical integration errors in the spatial domain technique. Further, the comparisons also show (implicitly) sufficient convergence of the series expansions applied for field continuation [Eqs. (15), (16)].

544 **3.5 Computational costs**

Regarding the computational costs for spectral domain forward modelling, a spherical harmonic 545 analysis of a single power of the THF took ~3 min on a standard office PC (input topography 546 band limited to degree 360, output coefficients of the THF to degree 2160). With the first six 547 powers of the THF taken into account (Fig. 5), the overall computation time for application of 548 the contribution scheme (Fig. 2) and synthesis of gravity effects with gradients over our $10^{\circ} \times 10^{\circ}$ 549 study area (360,000 points) was less than 1 hour. Opposed to this, the Newton integration 550 required more than 10,000 CPU hours on Western Australia's iVec supercomputer to provide 551 552 gravity effects over the same area. The computational costs of the space domain technique were relatively high because of the oversampling (20 arc-sec grid resolution for a degree-360 signal) 553 that was chosen to reduce discretisation errors down to the microGal-level. Polyhedral bodies 554 instead of prisms may not require such extreme oversampling to yield similarly low 555 discretisation errors, thus reducing the computational cost. 556

557 While in the case study the spectral technique was numerically more efficient than the spatial technique, there is a clear tendency of the spectral method becoming much more computationally 558 intensive as the degree increases. Application of the contribution scheme in Fig. 2 for a source 559 topography model to degree-2160 (10 km resolution) would require multiple harmonic synthesis 560 561 e.g., to degree and order 10,800 (five times oversampling) to "capture" the short-scale gravity signals at spatial scales less than 10 km. Currently, there is no software at hand to accurately 562 gauge the computational costs for this or other high-degree applications of the contribution 563 scheme. Importantly, increasing the spectral resolution will increase the computation times for 564 spectral forward modelling but not for the Newton integration if the above grid resolutions 565 566 remain the same.

567 4. Discussion

568 Gravity disturbances obtained from two entirely independent modelling techniques, but from the same input mass distribution, were compared over a worst-case test area, with special focus on 569 the spectral domain contributions made by (i) the integer powers p of the topography, and (ii) 570 571 multiples p of the input band width. Our numerical tests unambiguously demonstrate that a 572 band-limited topographic mass distribution implies a gravitational field with spectral power far beyond the input band limitation to n_{max} . Our test procedures were sensitive enough to 573 empirically show the relevance of the first three multiples ($N_{\text{max}} = 4 n_{\text{max}}$) of the input band, as 574 575 well as of higher-order contributions up to p = 6. This provides strong evidence for the validity of the contribution scheme introduced in Fig. 2, and thus justifies the statement that a band-576 limited topography generates (in good approximation) a full-spectrum gravity field. 577

The discrepancies among gravity from the spectral and spatial techniques were found to be 578 smaller than ~2 μ Gal when integer power contributions to $p_{max} = 6$ were evaluated, and the band 579 width of the potential was extended by a factor 4 over the band width of the topography (N_{max} = 580 $4n_{max}$). With a maximum signal strength of ~500 mGal (Fig. 6), this translates into a relative 581 error of 4×10^{-6} . To our knowledge, such a low relative error among the two forward modelling 582 techniques has not yet been reported in the literature. Compared to the uncertainty of the 583 universal gravitational constant G of about 1.2×10^{-4} [Mohr et al., 2012, p 72], these technique 584 discrepancies play a diminishing role for the accurate computation of topography-generated 585 gravity. All in all, the level of agreement between the forward modelling techniques can be 586 considered as excellent. 587

Holistically, our numerical comparisons provide valuable mutual feedback on the two techniques
applied, contributing to a better understanding of gravity forward modelling. In particular, the
comparisons demonstrate the following:

591 The importance of the computation point height. For the meaningful calculation of • gravity disturbances (or other functionals of the potential), computation points in both 592 techniques were located at the topography (other locations are possible). While the 593 attenuation of gravity with height and distance from the generating masses is accounted 594 for through the choice of computation points in the Newtonian integration, consideration 595 is possible in the spectral domain through gravity synthesis at the surface of the 596 topography. The excellent agreement between gravity from the two techniques (Table 1) 597 implicitly shows convergence of the gradient solution applied here [Eqs. (16), (17)]. 598

- The importance of higher-order integer contributions. For the accurate application of 600 • spectral domain forward modelling higher-order contributions made by integer powers of 601 the topography become increasingly relevant as the resolution of the input topography 602 increases [see also Hirt and Kuhn, 2012]. While the theory [e.g., Rummel et al., 1988; 603 Wieczorek and Phillips, 1998] clearly shows the need for higher-order contributions, 604 there are only few studies concerned with empirical verification of these terms based on 605 606 independent or external methods. Chambat and Valette [2005] showed the relevance of the squared topographic contribution (via a comparison with geopotential models). Our 607 technique comparisons now demonstrate the relevance of integer powers up to the sixth 608 power. 609
- The importance of multiples of the input band width. To accurately compute the gravitational field implied by a topographic mass distribution in the spectral domain, the contributions of the higher-order powers must be calculated in multiples of the input band width. The additional high-frequency gravity signals are significant (in our tests up to four times the input band width), as was shown by comparison with the independent Newtonian integration.
- 617

610

599

When the additional high-frequency signals remained [deliberately] unmodelled in our study 618 (i.e., $N_{\text{max}} = n_{\text{max}}$), the discrepancies among the two techniques would translate into relative errors 619 of ~1% ($N_{\text{max}} = n_{\text{max}} = 360$, cf. Table 1), but this will be larger for $N_{\text{max}} = n_{\text{max}} > 360$. Not shown 620 here for the sake of brevity, but a second numerical test with input band $N_{\text{max}} = n_{\text{max}} = 2160$ 621 vielded ~6.5% relative errors (34 mGal maximum discrepancy among both techniques vs. ~530 622 mGal signal) when neglecting signals beyond the input band width in the spectral technique. 623 624 These magnitudes are comparable with relative errors encountered in other studies comparing spectral and spatial forward modelling (0.8%, Novak and Tenzer [2013]; 3%, Kuhn and Seitz 625 626 [2005]; 4.5 %, Wild-Pfeiffer and Heck [2007], and ~10%, Wang et al. [2010]; Balmino et al. [2012], please see Sect. 1). Given our relative errors are at the level of 10^{-4} (0.01 %) for 627 $N_{\text{max}} = 2n_{\text{max}} = 720$, and diminish to the level of 4×10^{-6} (0.0004%) for $N_{\text{max}} = 4n_{\text{max}} = 1440$, it is 628

629 safe to conclude that [unmodelled und usually truncated] topography-generated gravity signals 630 beyond n_{max} are a key candidate for the discrepancies among spectral and spatial forward 631 modelling encountered in the aforementioned studies.

632 Wieczorek [2007] noted in his review paper on the character of the spectral forward modelling 633 equation [Eq. (12) in this paper]: "While the sum of Eq. 30 [ibid, p 19] is finite, and hence exact, 634 the number of terms grows linearly with spherical harmonic degree". However, our results and 635 the contribution scheme (Fig. 2) show that the sum used by Wieczorek [2007] cannot be used for 636 the exact computation of gravity implied by a given topography, because spectral consistency 637 among gravity and topography is assumed when using $N_{max} = n_{max}$. Rather, the exact calculation 638 of gravity from topography by harmonic expansion requires consideration of $N_{max} = p_{max}n_{max}$

639 [Eq. (10)], as shown in this study.

640 **5. Conclusions**

This paper has investigated the spectral (band width) inconsistency among spherical harmonic 641 topographic mass models and the generated gravitational field. A generalized contribution 642 scheme was introduced for the spectral domain forward modelling technique as a function of 643 644 integer powers and multiples of the input topography's band width. This new scheme mathematically describes the extension of the spectrum associated with the transformation of 645 topography to gravity based on Newton's law of gravitation. The short-scale gravity signals 646 647 generated by a band-limited topography can be surprisingly easily modelled in the spectral domain as shown in this paper. The validity of the contribution scheme was confirmed through 648 spectral analyses and space domain comparisons. 649

Modelling the additional high-frequency signals beyond the input band width has brought together the spatial domain and spectral domain forward modelling technique from a level of 10^{-2} to the level of better than 10^{-5} in terms of gravity disturbances. This is a considerable improvement by three orders of magnitude.

There are applications where the spectral inconsistency between topographic mass models and gravitational potential is entirely uncritical. For instance comparisons between observed and topography-implied gravitational fields in spherical harmonics (as in the calculation of spherical harmonic Bouguer gravity). This is because the fields are spectrally consistent in the gravity domain.

However, if the gravitational field generated by a spherical harmonic topography is to be exactly calculated, then multiples of the input topography's band width should be computed and evaluated in the spectral domain. Multiples of the input band width can be expected to become more relevant as the resolution increases (cf. Sect. 4). This has important implications for present and future ultra-high degree models of the topographic potential: For a standard degree-2160 topography model, the implied topographic potential would have to be modelled to (a coarsely estimated) degree of ~10,800 or higher if sufficient consistency between the two quantities is
sought. For an input band width of a topography model to degree and order 10,800 [e.g., *Balmino et al.*, 2012] would require spectral domain modelling to extremely high degree to
accurately compute the generated gravitational potential.

Finally, with the understanding of the spectral domain technique drawn from this study, 669 comparisons among spectral domain and spatial domain forward modelling can now be much 670 671 better utilized for a mutual validation of forward modelling software implementations and detailed testing of forward-modelling approaches. For instance, this can be helpful for (i) testing 672 integration formulas for gravity effects from mass bodies [Grombein et al., 2013, d'Urso 2014] 673 in the spatial domain technique, or (ii) investigating the convergence behaviour of series 674 675 expansions in the spectral domain in some not entirely undisputed cases (e.g., evaluations inside 676 the masses or inside the reference body).

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